

# Efficient Graph Generation with Graph Recurrent Attention Networks

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## Generative Model of Graphs

Model the distribution of graph  $G = (V, E)$ :

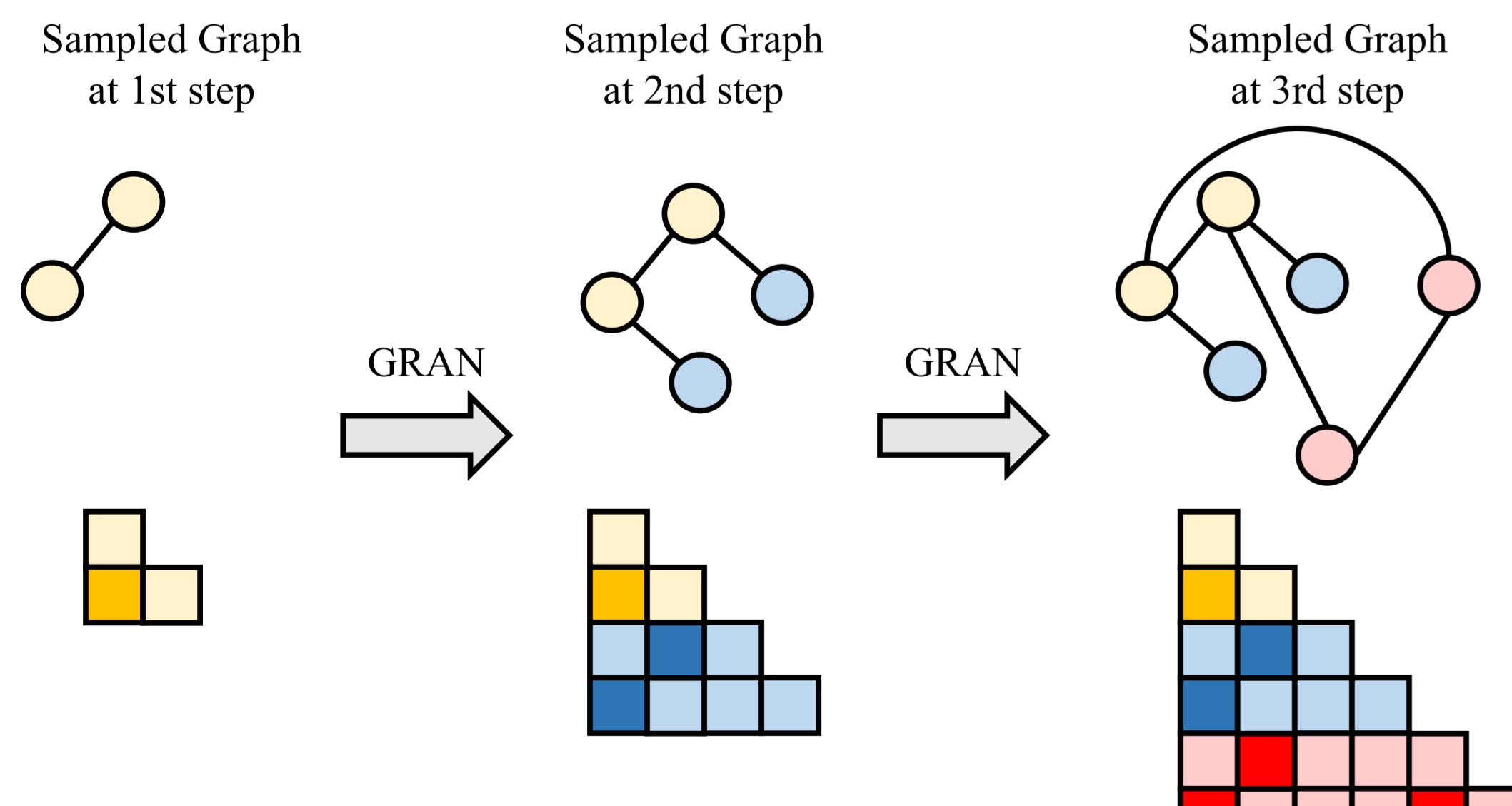
$$P(G) = \sum_{\pi} P(L^{\pi}, \pi),$$

where  $L^{\pi}$ : (binary) adjacency matrix  
 $\pi$ : node ordering.

## Contributions

- Our approach consists of  $O(N)$  **auto-regressive** generation steps, where a block of nodes and associated edges are generated per step.
- We propose an **attention-based GNN** that better utilizes the topology of the already generated graph, reduces the dependency on the node ordering, and distinguishes multiple newly added nodes.
- We capture the correlation between multiple generated edges via a **mixture of Bernoullis output distribution** per step.
- We approximate the likelihood by marginalizing over a family of **canonical node orderings**, e.g., DFS, BFS, or k-core.

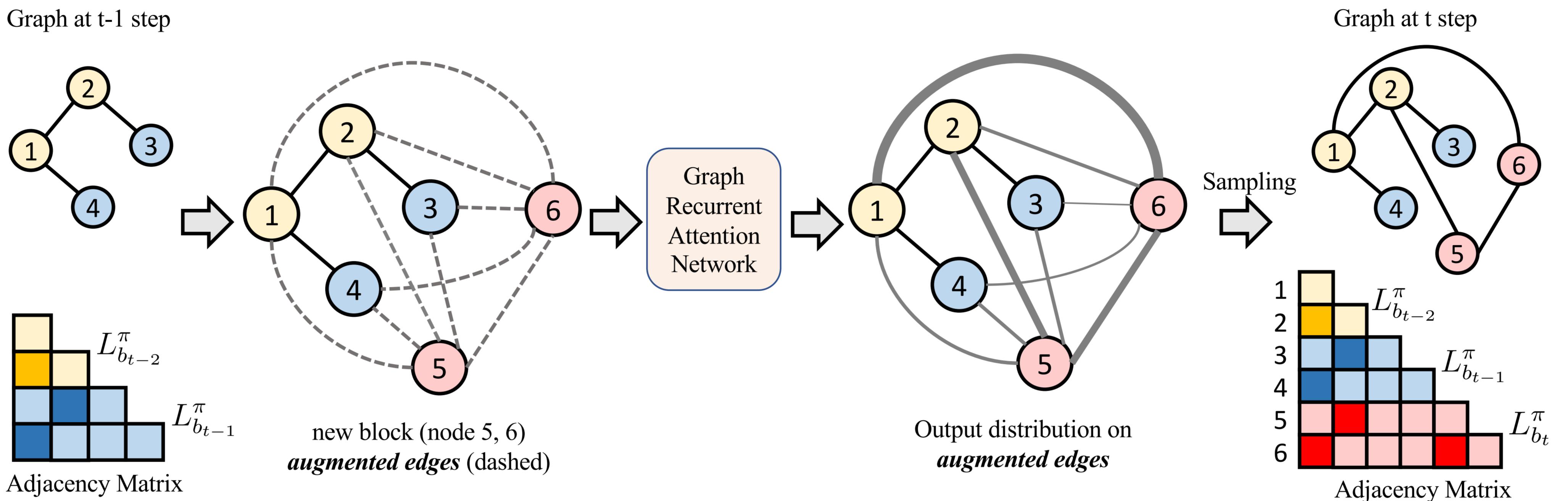
## Generation Process



- Varying the block size and the sampling stride permits the **efficiency-quality trade-off**.
- Breaking the dependency between generation steps allows **parallel training** with **sampled subgraphs**.

## Graph Recurrent Attention Networks (GRAN)

Auto-regressive Decomposition:  $p(L^{\pi}, \pi) = \prod_{t=1}^T p(L_{b_t}^{\pi} | L_{b_1}^{\pi}, \dots, L_{b_{t-1}}^{\pi})$



Initial Node Representation:  $h_{b_i}^0 = WL_{b_i}^{\pi} + b, \quad \forall i < t$

Message Passing:  $m_{ij}^r = f(h_i^r - h_j^r), \quad \tilde{h}_i^r = [h_i^r, x_i], \quad a_{ij}^r = \text{Sigmoid}(g(\tilde{h}_i^r - \tilde{h}_j^r)),$

$$h_i^{r+1} = \text{GRU}(h_i^r, \sum_{j \in \mathcal{N}(i)} a_{ij}^r m_{ij}^r).$$

Output Distribution:  $p(L_{b_t}^{\pi} | L_{b_1}^{\pi}, \dots, L_{b_{t-1}}^{\pi}) = \sum_{k=1}^K \alpha_k \prod_{i \in b_t} \prod_{1 \leq j \leq i} \theta_{k,i,j}$   
 $\alpha_1, \dots, \alpha_K = \text{Softmax} \left( \sum_{i \in b_t, 1 \leq j \leq i} \text{MLP}_{\alpha}(h_i^R - h_j^R) \right), \quad \theta_{1,i,j}, \dots, \theta_{K,i,j} = \text{Sigmoid} \left( \text{MLP}_{\theta}(h_i^R - h_j^R) \right)$

Approximated Likelihood:

$$P(G) = \sum_{\pi} P(L^{\pi}, \pi) \geq \sum_{\pi \in \mathcal{Q}} P(L^{\pi}, \pi) \quad \text{e.g. } \mathcal{Q} = \{\pi_{\text{BFS}}, \pi_{\text{DFS}}, \pi_{\text{degree descent}}, \pi_{\text{k-core}}, \pi_{\text{default}}\}$$

## Visualization

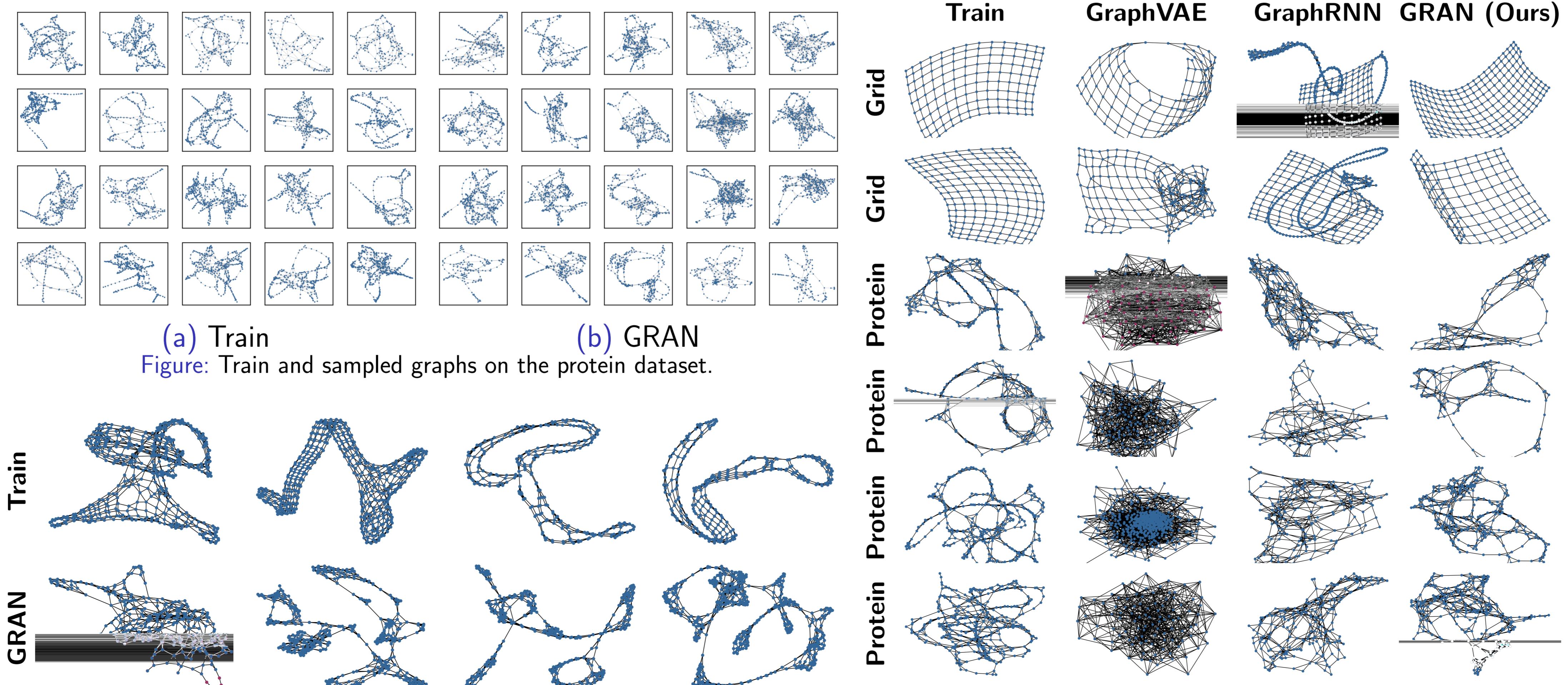


Figure: Train and sampled graphs on the 3D point cloud dataset.

## Experiments

Dataset	$ V _{\text{avg}}$	$ E _{\text{avg}}$	$ V _{\text{max}}$	$ E _{\text{max}}$
Grid	210	392	361	684
Protein	258	646	500	1575
3D Point Cloud	1377	3074	5037	10886

Table: Dataset statistics.

Dataset	Metric	Erdos-Renyi	GraphVAE*	GraphRNN-S	GraphRNN	GRAN
Grid	Deg.	0.79	$7.07e^{-2}$	0.13	$1.12e^{-2}$	<b><math>8.23e^{-4}</math></b>
	Clus.	2.00	$7.33e^{-2}$	$3.73e^{-2}$	<b><math>7.73e^{-5}</math></b>	$3.79e^{-3}$
	Orbit	1.08	0.12	0.18	<b><math>1.03e^{-3}</math></b>	$1.59e^{-3}$
	Spec.	0.68	$1.44e^{-2}$	0.19	<b><math>1.18e^{-2}</math></b>	$1.62e^{-2}$
Protein	Deg.	$5.64e^{-2}$	0.48	$4.02e^{-2}$	$1.06e^{-2}$	<b><math>1.98e^{-3}</math></b>
	Clus.	1.00	$7.14e^{-2}$	<b><math>4.79e^{-2}</math></b>	0.14	$4.86e^{-2}$
	Orbit	1.54	0.74	0.23	0.88	<b>0.13</b>
	Spec.	$9.13e^{-2}$	0.11	0.21	$1.88e^{-2}$	<b><math>5.13e^{-3}</math></b>
3D Point Cloud	Deg.	0.31	-	-	-	<b><math>1.75e^{-2}</math></b>
	Clus.	1.22	-	-	-	<b>0.51</b>
	Orbit	1.27	-	-	-	<b>0.21</b>
	Spec.	$4.26e^{-2}$	-	-	-	<b><math>7.45e^{-3}</math></b>

Table: For all MMD metrics, the smaller the better. \*: our own implementation, -: not applicable due to memory issue, Deg.: degree distribution, Clus.: clustering coefficients, Orbit: the number of 4-node orbits, Spec.: spectrum of graph Laplacian.

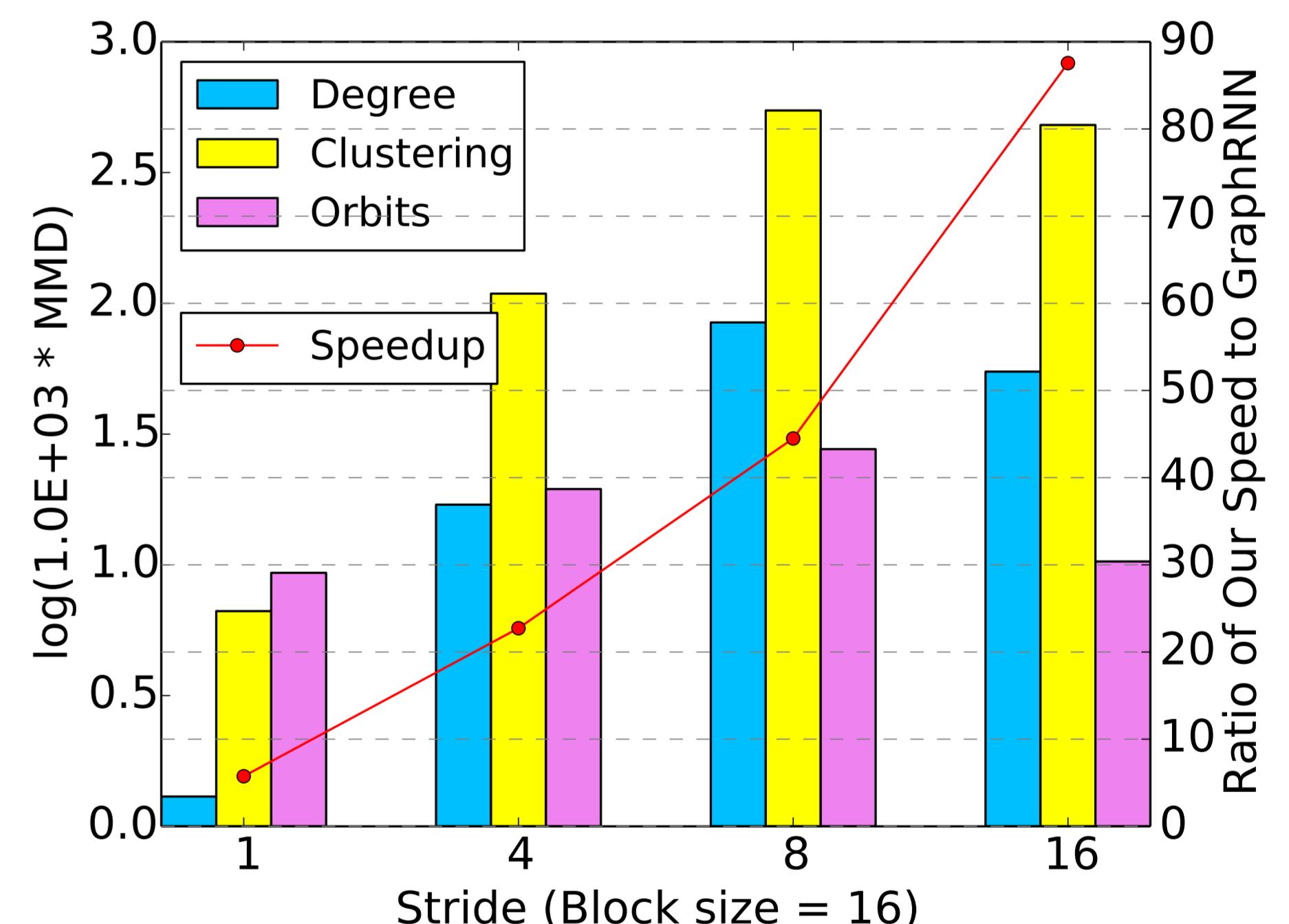


Figure: Efficiency vs. sample quality. The bar and line plots are the MMD (left y-axis) and speed ratio (right y-axis) respectively.

B	K	$\mathcal{Q}$	Deg.	Clus.	Orbit
1	1	{ $\pi_1$ }	$1.51e^{-5}$	0	$2.66e^{-5}$
1	20	{ $\pi_1$ }	$1.54e^{-5}$	0	$4.27e^{-6}$
1	50	{ $\pi_1$ }	$1.70e^{-5}$	0	$9.56e^{-7}$
1	20	{ $\pi_1, \pi_2$ }	$6.00e^{-2}$	0.16	$2.48e^{-2}$
1	20	{ $\pi_1, \pi_2, \pi_3$ }	$8.99e^{-3}$	$7.37e^{-3}$	$1.69e^{-2}$
1	20	{ $\pi_1, \pi_2, \pi_3, \pi_4$ }	$2.34e^{-2}$	$5.95e^{-2}$	$5.21e^{-2}$
1	20	{ $\pi_1, \pi_2, \pi_3, \pi_4, \pi_5$ }	$4.11e^{-4}$	$9.43e^{-3}$	$6.66e^{-4}$
4	20	{ $\pi_1$ }	$1.69e^{-4}$	0	$5.04e^{-4}$
8	20	{ $\pi_1$ }	$7.01e^{-5}$	$4.89e^{-5}$	$8.57e^{-5}$
16	20	{ $\pi_1$ }	$1.30e^{-3}$	$6.65e^{-3}$	$9.32e^{-3}$

Table: Ablation study. B: block size, K: number of Bernoulli mixtures,  $\pi_1$ : DFS,  $\pi_2$ : BFS,  $\pi_3$ : k-core,  $\pi_4$ : degree descent,  $\pi_5$ : default.

Code (Pytorch): <https://github.com/lrjconan/GRAN>